ME218a Midterm Exam Due by 4pm on 10/23/98

Name:_____

I Certify that I have taken this examination in compliance with the Stanford University Honor Code.

Sign Here

Include this as the cover sheet for you solutions

The Midterm Web Forum is at:

http://36.37.0.17/HyperNews/get/Midterm98.html

Other useful sites

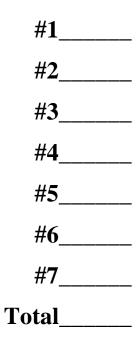
http://www.fairchildsemi.com/catalog/Digital.html

http://www.ti.com/sc/docs/asl/home.htm

http://mot2.mot-sps.com/logic/

Midterm Examination for ME 218a

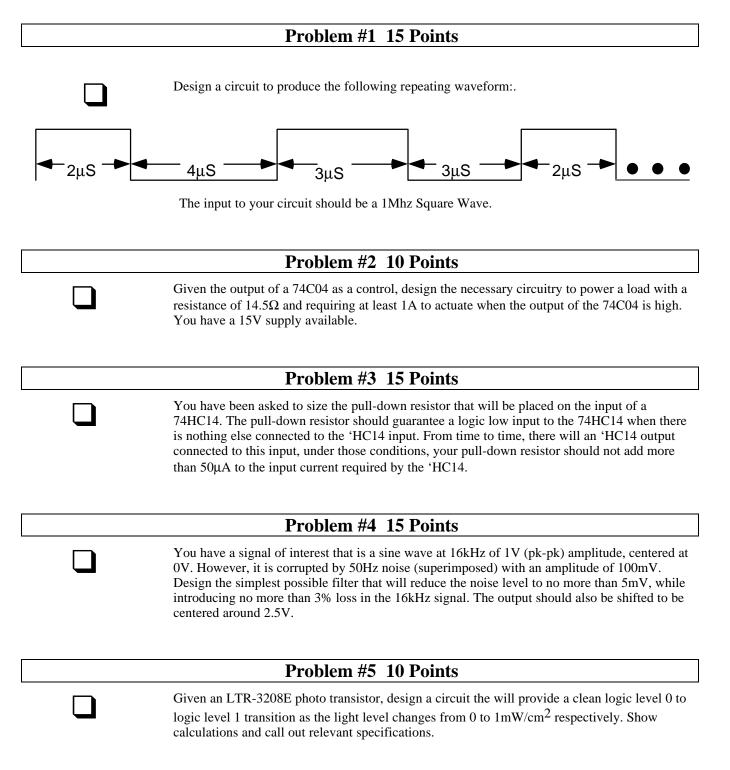
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Unless otherwise stated, the power supply for all problems is 5V.



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Problem #6 10 Points

Design a circuit that will produce a 0.5S high pulse for every input pulse like that shown below:

2μS

These pluses will occur at random intervals, but never separated by less than 0.5S.

Problem #7 25 Points

You have been asked to design the logic for a speed regulator. The input to your circuit will be a pulse train coming from the motor that is being controlled. The goal is to control the speed of the motor such that the pulse train is at approximately 100Hz. At a constant speed, this signal will be a square wave. Your regulator circuit should produce two outputs: Accelerate and Brake. If the speed is less than 96Hz, you should activate (set high) the Accelerate line and not the Brake Line. If the speed is at or above 120Hz, you should activate (set high) the Brake line and not the Accelerate Line. If the speed is within the range, neither signal should be active. Based on the inertia of the driven system, you have been told that the command signals must be updated at least 8 times a second and that the maximum

acceleration/deceleration rate is 40Hz/Sec.. From another part of the system, a highly accurate 32.768kHz square wave is available for your use. Complete your design using HC family logic devices. Be sure to label all IC pins in your schematic with their functional label, not just pin numbers.

Note: Don't get carried away with misplaced accuracy here. Take a look at the width of the acceptable speed range. Consider the impact of the conditions that you are evaluating. For instance, if you are at 96Hz and you fail to remove the accelerate signal: no big deal, you will continue to accelerate for another 1/8sec. taking you to 101Hz, where you should certainly remove the accelerate signal. **Remember:** start with blocks identifying the functions that you need.